

ECE 461/661 - Test #2: Name _____

Feedback and Root Locus - Fall 2025

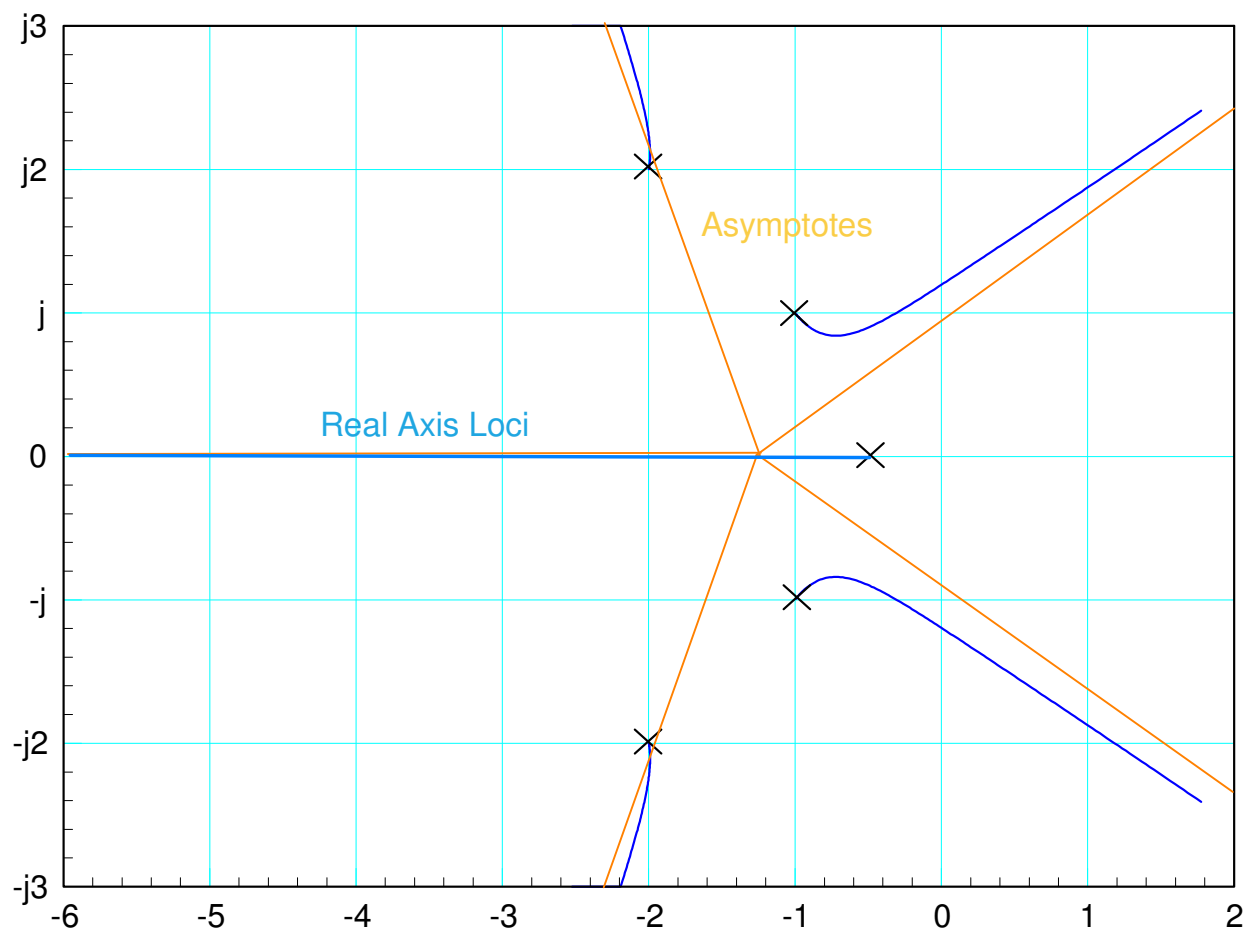
Root Locus

1) The root locus of $G(s)$ is shown below.

$$G(s) = \left(\frac{10}{(s+0.5)(s+1+j)(s+1-j)(s+2+j2)(s+2-j2)} \right)$$

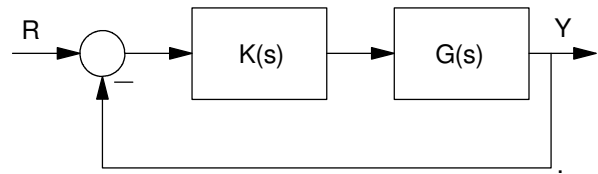
Determine the following

Departure Angle from the pole at $-2+j2$	Departure Angle from the pole at $-1+j1$	Real Axis Loci
79.69 degrees	-53.13 degrees	$(-0.5, -\infty)$
Breakaway Points (approx)	Asymptotes	jw Crossing(s)
none	show on graph	$j1.1962$



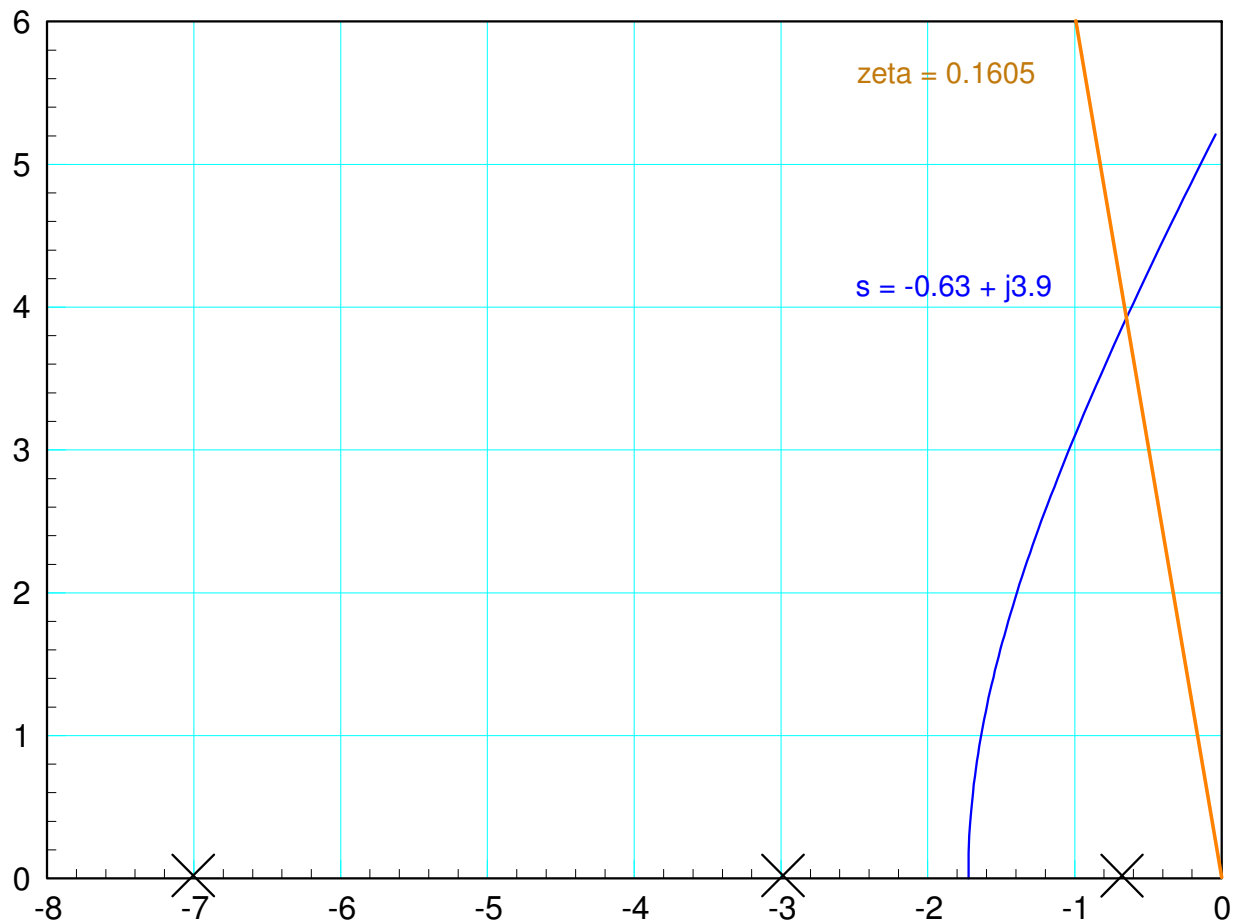
Gain Compensation

2) Determine the gain ($K(s) = k$) so that the feedback system has 60% overshoot for a step input. Also determine the closed-loop dominant pole(s) and error constant, K_p



$$G(s) = \left(\frac{10}{(s+0.7)(s+3)(s+7)} \right)$$

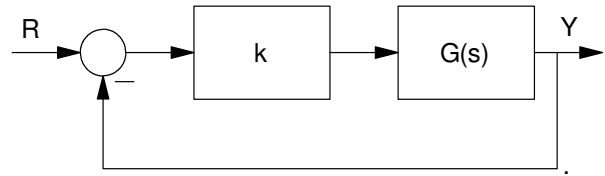
Damping Ratio 60% overshoot	Angle of Pole	k 60% overshoot	Closed Loop Dominant Pole(s)	K _p Error Constant
0.1605	80.76 deg	13.53	$s = -0.6408 + j3.9393$	9.2054 $13.53 * 0.6803$



Lead/PI Compensation

3) Design a compensator, $K(s)$, so that the closed-loop system has

- No error for a step input
- Closed-Loop dominant poles at $s = -3 + j2$, and
- Finite gain as $s \rightarrow \infty$ (i.e. have at least as many poles as zeros)



$$G(s) = \left(\frac{10}{(s+0.7)(s+3)(s+7)} \right)$$

Let

$$K(s) = \left(\frac{k(s+0.7)(s+3)}{s(s+a)} \right)$$

$$GK = \left(\frac{10k}{s(s+7)(s+a)} \right)$$

Evaluate what we know at the design point

$$\left(\frac{10}{s(s+7)} \right)_{s=-3+j2} = 0.6202 \angle -172.875^\circ$$

To make the angle 180 degrees

$$\angle(s+a) = 7.125^\circ$$

$$a = \left(\frac{2}{\tan(7.125^\circ)} \right) + 3 = 19.06$$

Now evaluate what we know

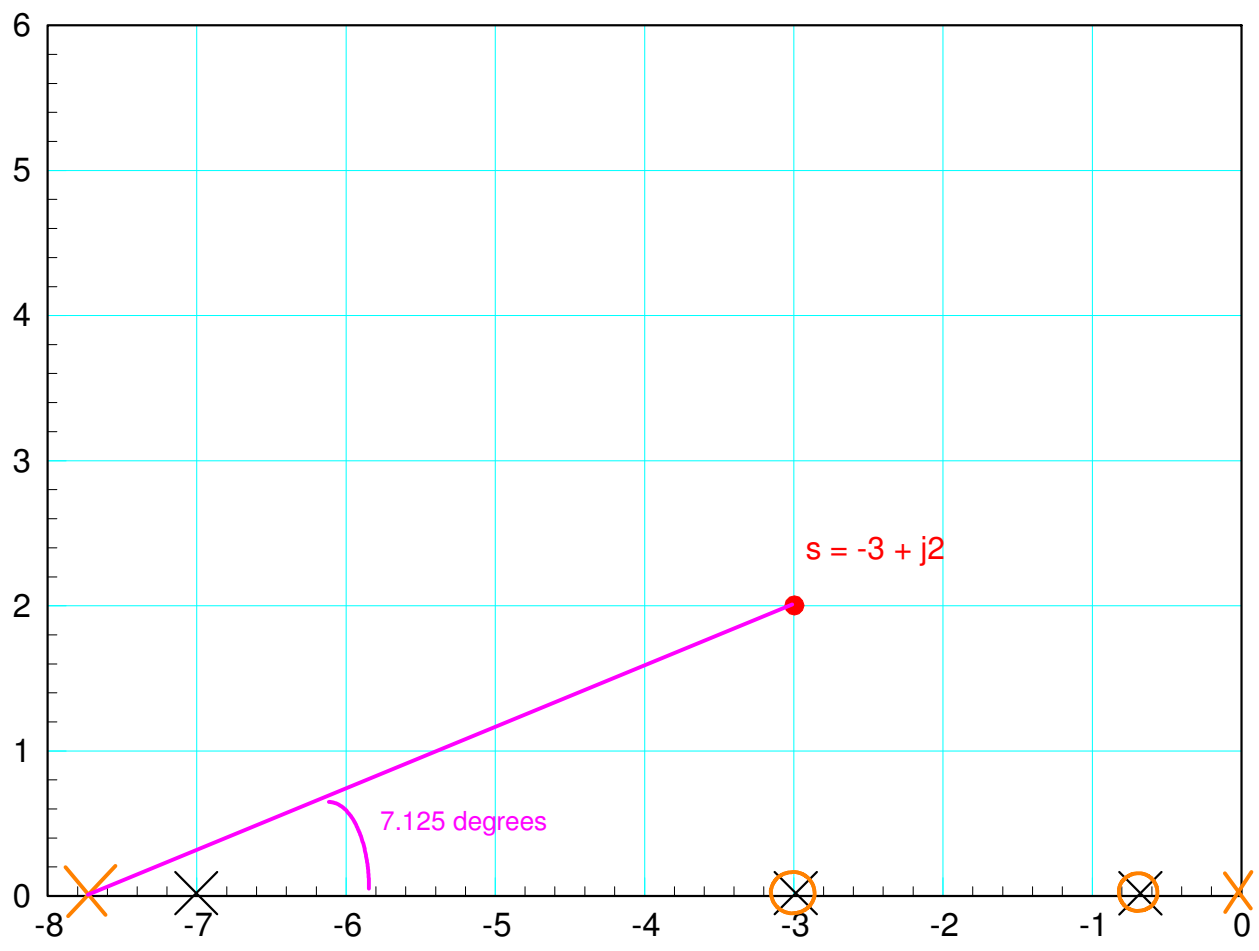
$$\left(\frac{10}{s(s+7)(s+19)} \right)_{s=-3+j2} = 0.0385 \angle 180^\circ$$

k is then

$$k = \frac{1}{0.0385} = 26.00$$

and

$$K(s) = \left(\frac{26(s+0.7)(s+3)}{s(s+26)} \right)$$



Compensator Design (hardware)

4) Design a circuit to implement $K(s)$

$$K(s) = \left(\frac{25(s+3)(s+7)}{s(s+10)} \right)$$

Rewrite as

$$5 \left(\frac{s+3}{s+10} \right) \cdot 5 \left(\frac{s+7}{s} \right)$$

